# Constraint Programming - Filtering : Part 1 -

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### 1 Filtering Domains with Constraints

#### **2** Principle of Constraint Propagation

### Outline

#### 1 Filtering Domains with Constraints

2 Principle of Constraint Propagation

# Each constraint represents a "sub-problem" from which some *inconsistent* values can be deleted.

Inconsistent values belong to no solution (of the sub-problem).

Several levels/types of filtering can be defined. For the moment, we only cite:

- AC (Arc Consistency): all inconsistent values are identified and deleted
- BC (Bounds Consistency): inconsistent values corresponding to the bounds of the domains are identified and deleted

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#### Constraint x < y with

- dom(x) = 10..20
- dom(y) = 0..15

After AC filtering, we obtain:

- dom(x) = 10..14
- dom(y) = 11..15

After BC filtering, we obtain:

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Constraint w + 3 = z with

- $dom(w) = \{1, 3, 4, 5\}$
- $dom(z) = \{4, 5, 8\}$

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- an allowed tuple, or tuple accepted by c, is an element of A = rel(c)
- a valid tuple is an element of  $V = \prod_{x \in scp(c)} dom(x)$
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Let  $c_{xyz}$  be a ternary constraint, and let us suppose that  $dom(x) = dom(y) = \{a, b\}$  and  $dom(z) = \{b, c\}$ . We have:

- $A = rel(c_{xyz})$
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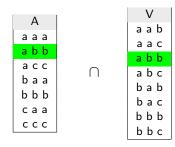
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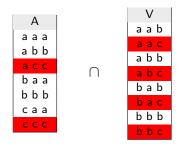
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(z, c) has no support X

### Definition

A constraint c is arc-consistent (AC) iff  $\forall x \in scp(c)$ ,  $\forall a \in dom(x)$ , there exists a support of (x, a) on c, i.e., a support  $\tau$  on c such that  $\tau[x] = a$ .

### Example.

Let x and y be two variables such that  $dom(x) = dom(y) = \{1, 2\}$ , and let x = y be a binary constraint.

- the tuple au = (1,2) //  $au[x] = 1 \wedge au[y] = 2$ 
  - is valid
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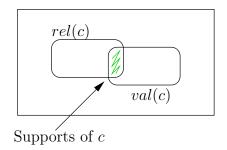
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## Supports

In other words, the supports on a constraint c are those tuples that are present in the intersection of :

- the set of allowed tuples: rel(c)
- the set of valid tuples:  $val(c) = \prod_{x \in scp(c)} dom(x)$

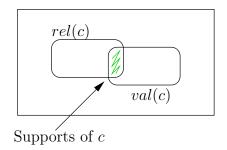


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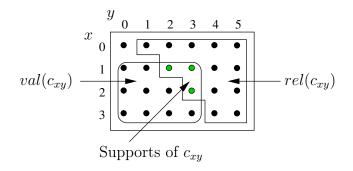
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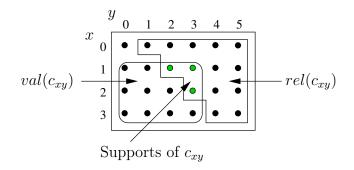
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# AC Algorithm

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A value (x, a) is *arc-inconsistent* on a constraint c when there is no support of (x, a) on c.

### Definition

An AC algorithm for a constraint c is an algorithm that removes all values that are arc-inconsistent on c; the algorithm is said to enforce/establish AC on c.

Here is an AC algorithm that can be used in theory with any constraint c.

**Algorithm 1:** filterAC(*c*: Constraint)

```
for each variable x \in scp(c) do
for each value a \in dom(x) do
if \neg seekSupport(c, x, a) // function to be implemented
then
remove a from dom(x)
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Algorithm 2: filterAC(c: Constraint)for each variable x \in scp(c) dofor each value a \in dom(x) doif \neg seekSupport(c, x, a) // function to be implementedthen______ remove a from dom(x)
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## Proposition A constraint allDifferent(X) is AC iff $\forall X' \subseteq X$ , $|dom(X')| = |X'| \Rightarrow \forall x \in X \setminus X', dom(x) = dom(x) \setminus dom(X')$ where $dom(X') = \bigcup_{x' \in X'} dom(x')$

#### Remark.

A subset X' of variables such that |dom(X')| = |X'| is called a Hall set.

#### Example.

The set of variables  $\{x, y, z\}$  such that:

- $dom(x) = \{a, b\},\$
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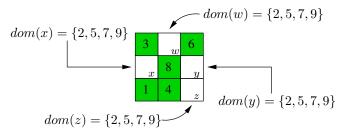
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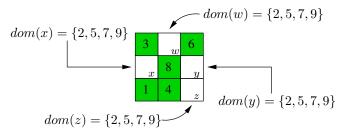
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Can we filter?

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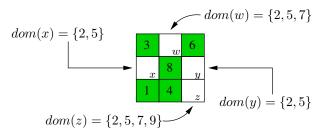


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The same constraint as previously, but variables have different domains.

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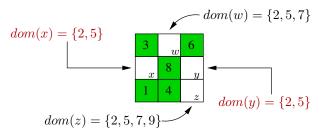
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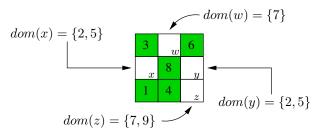
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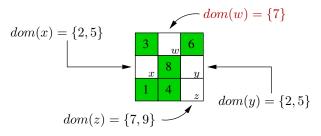
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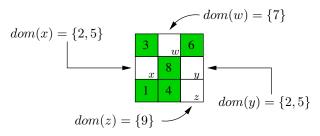
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A constraint cardinality(X, V, L, U) forces the variables in X to take their values in V with the restriction that each value  $v_i$  in V is assigned at least  $L(v_i)$  times and at most  $U(v_i)$  times.

### Example.

Three sets:

- Agents = { Peter, Paul, Mary, John, Bob, Mike, Julia }
- Days = {Monday, Tuesday, ..., Sunday}
- Activities = {M(orning), D(ay), N(ight), B(ackup), O(ff)}.
- We want a roster that looks like:

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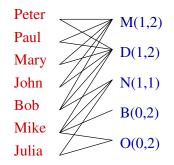
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	Мо	Tu	We	Th	Fr	Sa	Su
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Paul	0	0	D	D	Μ	Μ	В
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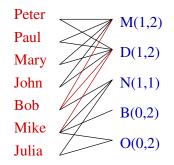
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- $L = \{1, 1, 1, 0, 0\}$
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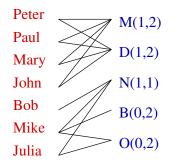
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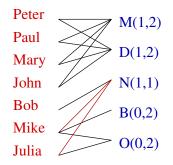
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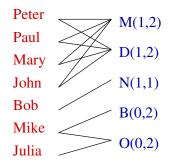
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- $U = \{2, 2, 1, 2, 2\}.$



Domains of variables w, x, y and z

dom					
W	X	у	Ζ		
1	1	2	2		
2	2	3	3		
3	3	4	4		

Constraint  $c_{wxyz}$ :  $w + 2x + 4y + 5z \ge 42$ 

Domains of variables w, x, y et z after AC filtering of  $c_{wxyz}$ 

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W	X	y	Ζ		
1	+	2	2		
2	2	<del>3</del>	<del>3</del>		
3	3	4	4		

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		doi	m	
Domains of variables	W	X	у	Ζ
w, x, y and z	1	1	1	1
			2	2

Constraint  $c_{wxyz}$  :  $w + x + y + z \neq 5$ 

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	W	X	y	Ζ
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# AC Filtering for sum : $U \ge \sum_{i=1}^{r} c_i x_i \ge L$

Possibility of using dynamic programming:

- construction of a graph (Knapsack)
- reduction of the graph
- use of a constraint mdd from the reduced graph

### Warning

Pseudo-polynomial Complexity  $O(rU^2)$ 

### Example.

Illustration of this approach with:

- the constraint  $12 \ge 2x_1 + 3x_2 + 4x_3 + 5x_4 \ge 10$
- where the domain of each variable is  $\{0,1\}$ .

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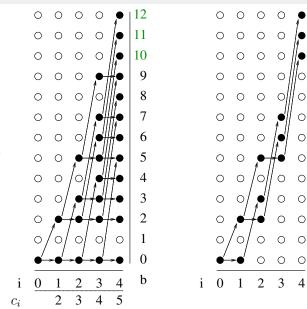
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# Example

Knapsack Graph



Reduced Knapsack Graph

b

### Constructive Disjunction

Enforcing AC on a meta-constraint  $or(c_1, c_2)$  can be achieved by *constructive disjunction*: for each variable *x*, dom(x) is the union of the domains of *x* obtained after AC filtering on  $c_1$  and AC filtering on  $c_2$ .

#### Example.

Let x be a variable such that  $dom(x) = \{1, 2, 3\}$  and the meta-constraint or(x = 1, x = 2).

AC on x = 1 yields dom<sup>1</sup>(x) = {1} AC on x = 2 yields dom<sup>2</sup>(x) = {2}

AC on or(x = 1, x = 2) reduces dom(x) to  $dom^{1}(x) \cup dom^{2}(x) = \{1, 2\}$ 

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# AC Filtering for and (meta-constraint)

### Proposition

AC on the conjunction  $and(c_1,c_2)$  is with respect to AC enforced independently on  $c_1$  and  $c_2$ :

- generally stronger,
- equivalent when  $|scp(c_1) \cap scp(c_2)| \le 1$

### Example

Let x and y two variables such that  $dom(x) = dom(y) = \{1, 2, 3\}$  and the meta-constraint  $and(x \neq y, x \leq y)$ .

- AC on  $x \neq y$  as well as AC on  $x \leq y$  have no effect
- AC on and  $(x \neq y, x \leq y)$  permits to have:
  - *dom*(*x*) reduced to {1,2}
  - dom(y) reduced to {2,3}

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#### 1 Filtering Domains with Constraints

#### 2 Principle of Constraint Propagation

### Definition A constraint network P is AC iff each constraint of P is AC.

### Definition

Computing the AC-closure of a constraint network P is the fact of removing all arc-inconsistent of P (when considering any constraint of P).

# May we sollicit each constraint once (for filtering) in order to compute the AC-closure?

NO because when some values are filtered out by a constraint, this can give new opportunities to other constraints to filter again.

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# Constraint Propagation Algorithm

Algorithm 4: constraintPropagationOn(P: CN): Boolean

return true

#### Remark.

If each call *c.filter*() enforces AC on *c*, then the algorithm computes the AC-closure of *P*.

# Constraint Propagation Algorithm

Algorithm 5: constraintPropagationOn(P: CN): Boolean

return true

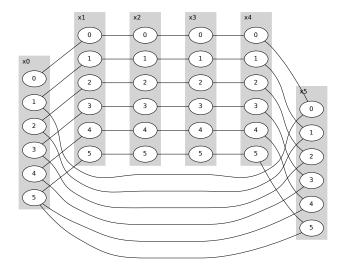
#### Remark.

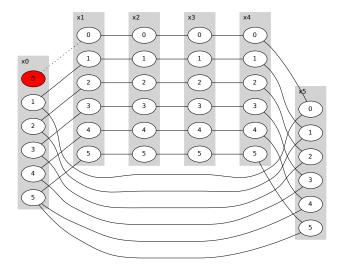
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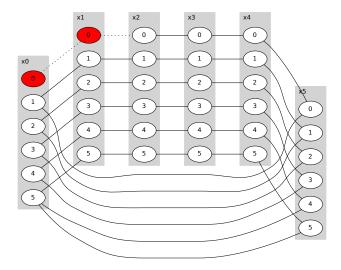
# Domino Problem

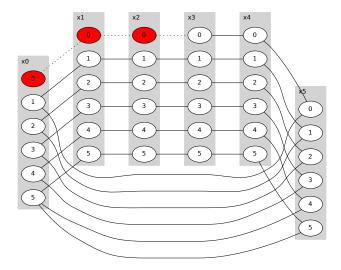
The instance domino-6 is represented by the following CN P:

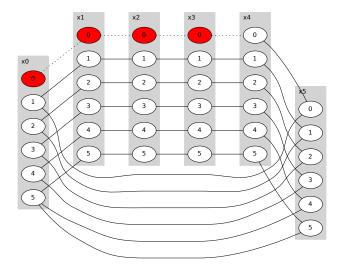
• 
$$vars(P) = \{$$
  
 $x_0 \text{ with } dom(x_0) = \{0, 1, 2, 3, 4, 5\},$   
 $x_1 \text{ with } dom(x_1) = \{0, 1, 2, 3, 4, 5\},$   
 $x_2 \text{ with } dom(x_2) = \{0, 1, 2, 3, 4, 5\},$   
 $x_3 \text{ with } dom(x_3) = \{0, 1, 2, 3, 4, 5\},$   
 $x_4 \text{ with } dom(x_4) = \{0, 1, 2, 3, 4, 5\},$   
 $x_5 \text{ with } dom(x_5) = \{0, 1, 2, 3, 4, 5\},$   
 $\}$   
•  $ctrs(P) = \{$   
 $x_0 = x_1,$   
 $x_1 = x_2,$   
 $x_2 = x_3,$   
 $x_3 = x_4,$   
 $x_4 = x_5,$   
 $(x_0 = x_5 + 1 \land x_0 < 5) \lor (x_0 = x_5 \land x_0 = 5)$   
 $\}$ 

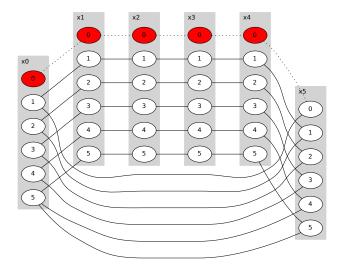


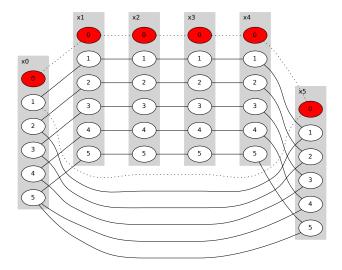


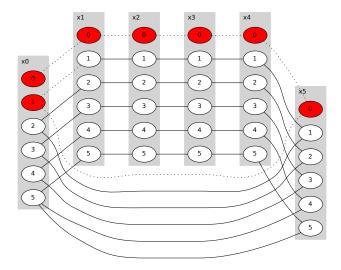


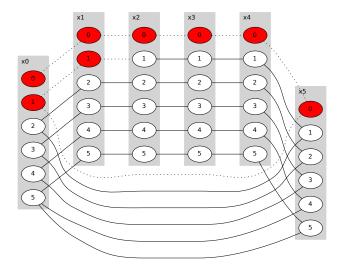


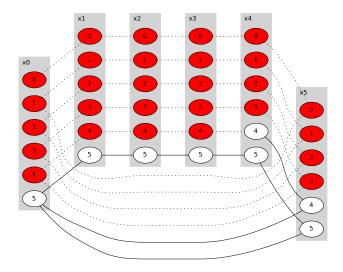


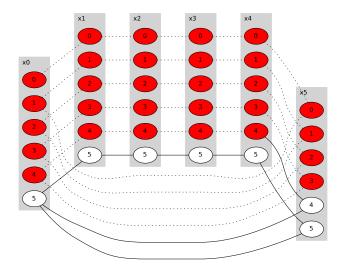


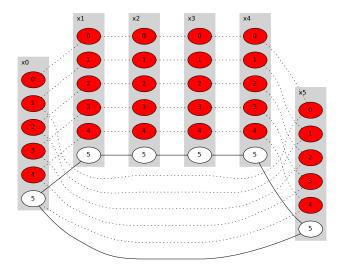












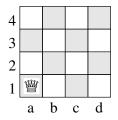
### Constraint Propagation on queens-4

For the 4-queens instance, we have:

• 
$$vars(P) = \{$$
  
 $x_a \text{ with } dom(x_a) = \{1, 2, 3, 4\}$   
 $x_b \text{ with } dom(x_b) = \{1, 2, 3, 4\}$   
 $x_c \text{ with } dom(x_c) = \{1, 2, 3, 4\}$   
 $x_d \text{ with } dom(x_d) = \{1, 2, 3, 4\}$   
•  $ctrs(P) = \{$   
 $x_a \neq x_b \land |x_a - x_b| \neq 1,$   
 $x_a \neq x_c \land |x_a - x_c| \neq 2,$   
 $x_a \neq x_d \land |x_a - x_c| \neq 2,$   
 $x_b \neq x_c \land |x_b - x_c| \neq 1,$   
 $x_b \neq x_d \land |x_b - x_d| \neq 2,$   
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}

#### Exercice

After taking the decision  $x_a = 1$ , what is the AC-closure of *P*?



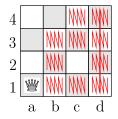
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### Exercice

After taking the decision  $x_a = 1$ , the AC-closure of *P* is:



### Exercice

Let P be the following CN:

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 $x_1 \text{ with } dom(x_1) = \{1, 2, 3\},$   
 $x_2 \text{ with } dom(x_2) = \{1, 2, 3\},$   
 $x_3 \text{ with } dom(x_3) = \{1, 2, 3\},$   
 $x_4 \text{ with } dom(x_4) = \{1, 2, 3\}$   
}  
•  $ctrs(P) = \{$   
 $x_1 \neq x_2,$   
 $x_2 + x_3 \leq x_1,$   
 $x_2 + x_4 \geq 2 * x_1,$   
}

Simulate the process of constraint propagation on P (that is to say, compute the AC-closure of P).