

# Modéliser des problèmes plus complexes d'optimisation sous contraintes

- Différentes approches pour la modélisation
- Modélisation simple en MiniZinc
- Modélisation avancée en MiniZinc
  - Predicats:
    - Contraintes globales
    - Contraintes définies par l'utilisateur et tests
    - Fonctions complexes
  - Gestion de variables locales
  - Négation et fonctions partielles
  - Efficacité
    - Différents modèles possibles
    - Contraintes redondantes

# Predicats

- MiniZinc permet de prendre en charge des contraintes complexes via des prédicats qui peuvent être
  - Traités par le solveur ou
  - Définis par l'utilisateur
- Une définition de prédicat est de la forme
  - `predicate <pred-name> ( <arg-def> ... <arg-def> ) = <bool-exp>`
- Un argument de définition est une déclaration de type MiniZinc
  - `int:x, array[1..10] of var int:y, array[int] of bool:b`
- **Note** les tableaux ne sont pas forcément de taille fixe

# Contraintes Globales: alldifferent

- `alldifferent(array[int] of var int:x)`
- Défini un sous problème d'affectation : toutes les vars de x doivent avoir des valeurs différentes

```
include "alldifferent.mzn";  
var 1..9: S;  
var 0..9: E;  
var 0..9: N;  
var 0..9: D;  
var 1..9: M;  
var 0..9: O;  
var 0..9: R;  
var 0..9: Y;  
  
constraint 1000 * S + 100 * E + 10 * N + D  
           + 1000 * M + 100 * O + 10 * R + E  
           = 10000 * M + 1000 * O + 100 * N + 10 * E + Y;  
  
constraint alldifferent([S,E,N,D,M,O,R,Y]);  
  
solve satisfy;
```

- On doit insérer le `include` , ou inclure toutes les globales avec `include "globals.mzn"`

# Contraintes Globales: inverse

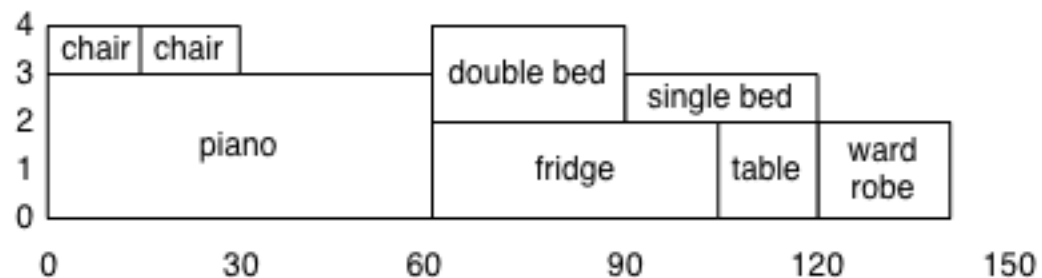
- `inverse(array[int] of var int:f, array[int] of var int:if)`
  - $f[i] = j \Leftrightarrow if [j] = i$  (*if* is the inverse function  $f^{-1}$ )
- Utile pour des problèmes d'affectation qui nécessitent les deux visions
- Exemple avec l'affectation de tâches à des ouvriers.
- `array[1..n] of var 1..n: task;`  
`array[1..n] of var 1..n: worker;`  
`constraint inverse(task,worker);`

# Contraintes Globales : cumulative

- Pour l'utilisation cumulative de ressources
- `cumulative(array[int] of var int: s, array[int] of var int: d, array[int] of var int: r, var int: b)`
  - Un ensemble de tâches avec une date de début  $s$ , une durée  $d$  et une utilisation de ressource  $r$ .  
On dispose d'au plus  $b$  ressources
  - % Déménagement piano, fridge, double bed, single bed, wardrobe chair, chair, table

`d = [60, 45, 30, 30, 20, 15, 15, 15];`

`r = [3, 2, 2, 1, 2, 1, 1, 2]; b = 4;`



# Contraintes Globales : table

- Contraint un tableau a être une ligne d'une table :

- `table(array[int] of var int: x, array[int,int] of int:t)`

- Options pour des voitures (car sequencing)

- `% doors, sunroof, speakers, satnav, aircon`

```
models = [| 5, 0, 0, 0, 0 % budget hatch
```

```
          | 4, 1, 2, 0, 0 % standard saloon
```

```
          | 3, 1, 2, 0, 1 % standard coupe
```

```
          | 2, 1, 4, 1, 1 |]; % sports coupe
```

```
constraint table(options, models);
```

# Contraintes définies par l'utilisateur

MiniZinc (contrairement à beaucoup de langages de modélisation) autorise l'utilisateur à définir ses propres contraintes :

- predicats (var bool)
- tests (bool)

N-reines :

```
int: n;  
array [1..n] of var 1..n: q;
```

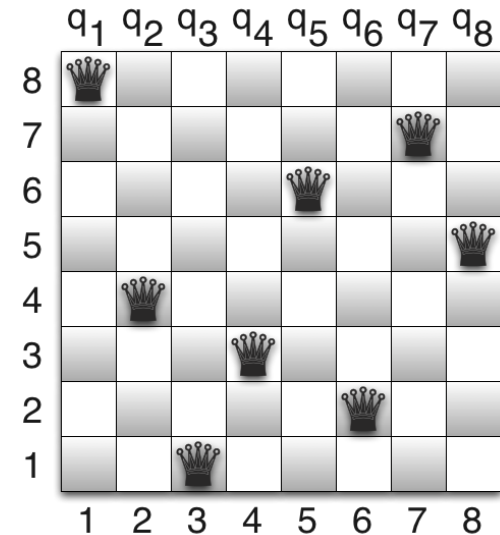
```
predicate
```

```
noattack(int: i, int: j, var int: qi, var int: qj) =  
    qi != qj /\ qi + i != qj + j /\ qi - i != qj - j;
```

```
constraint
```

```
forall (i in 1..n, j in i+1..n) (noattack(i, j, q[i], q[j]));
```

```
solve satisfy;
```

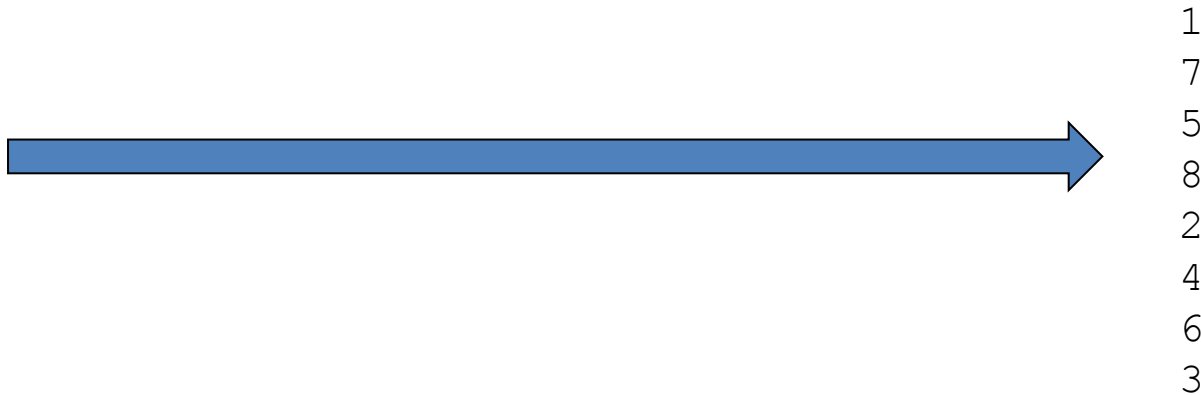


# Formats de sortie complexes

- Parfois l'affichage est éloigné du problème:

Reines

- Les variables sont les colonnes, sortie par ligne





# Formats de sortie complexes

- Solution: format plus complexe via une expression d'affichage
- `output [ if fix(q[j]) == i then "Q" else "." endif ++  
if j == n then "\n" else "" endif | i,j in 1..n];`

```
Q.....  
.....Q.  
.....Q..  
.....Q.  
.Q.....  
.....Q..  
.....Q..  
..Q.....
```

# Reflection Functions

- To help write generic tests and predicates, various reflection functions return information about array index sets, var set domains and decision variable ranges:
  - `index_set(<1-D array>)`
  - `index_set_1of2(<2-D array>)`, `index_set_2of2(<2-D array>)`
  - ...
  - `dom(<arith-dec-var>)`, `lb(<arith-dec-var>)`, `ub(<arith-dec-var>)`
  - `lb_array(<var-set>)`, `ub_array(<var-set>)`
- The latter class give "safe approximations" to the inferred domain, lowerbound and upperbound
  - Currently in `mzn2fzn` this is the declared or inferred bound

# Extending assertions

- For predicates we introduce an extended assertion
  - `assert(<bool-exp>, <string>, <bool-exp>)`
- If first `<bool-exp>` evaluates to false prints `<string>` and aborts otherwise evaluates second `<bool-exp>`
- Useful to check user-defined predicate is called correctly

# Using Reflection

- The disjunctive constraint:
  - cumulative where resource bound is 1 and all tasks require 1 resource.
  - include "cumulative.mzn";  
predicate disjunctive(array[int] of var int:s,  
array[int] of int:d) =  
assert(index\_set(s) == index\_set(d),  
"disjunctive: first and second arguments " ++  
"must have the same index set",  
cumulative(s, d, [ 1 | i in index\_set(s) ], 1)  
);

# All\_different

- Write a predicate defining the alldifferent constraint that takes a 1-D array:

`alldifferent(array[int] of var int:x)`

# Local Variables

- It is often useful to introduce **local variables** in a test or predicate
- The let expression allows you to do so  
`let { <var-dec>, ... } in <exp>`  
(It can also be used in other expressions)
- The var declaration can contain decision variables and parameters
  - Parameters must be initialized
- Example:  
`let {int: l = lb(x), int: u = ub(x) div 2, var l .. u: y} in  
x = 2*y`

# Exercise: Local Variables

```
var -2..2: x1;  
var -2..2: x2;  
var -2..2: x3;  
var int: ll;  
var int: uu;  
constraint even(2 * x1 - x2 * x3);  
predicate even(var int:x) =  
  let { int: l = lb(x), int: u = ub(x) div 2, var l..u: y } in  
  x = 2 * y  $\wedge$  l = ll  $\wedge$  u = uu;  
output["l = ",show(ll), " u = ",show(uu), "\n"];
```

What prints out?

# Complex use of local variables

predicate `lex_less_int`(array[int] of var int: x,

array[int] of var int: y) =

let { int: lx = min(index\_set(x)), int: ux = max(index\_set(x)),

int: ly = min(index\_set(y)), int: uy = max(index\_set(y)),

int: size = min(ux - lx, uy - ly),

array[0..size+1] of var bool: b }

in

b[0]  $\wedge$

forall(i in 0..size) (

b[i] = ( x[lx + i] <= y[ly + i]  $\wedge$

( x[lx + i] < y[ly + i]  $\vee$  b[i+1] ) )

)

$\wedge$

b[size + 1] = (ux - lx < uy - ly);

X is lexicographically less than Y



# Partial functions

- Given declarations

var 0..1: x;

var 0..5: i;

array[1..4] of int:a = [1,2,3,4];

- What are expected solutions for
  - constraint  $1 \neq 1 \text{ div } x$ ;
  - constraint  $\text{not}(1 == 1 \text{ div } x)$ ;
  - constraint  $x < 1 \vee 1 \text{ div } x \neq 1$ ;
  - constraint  $a[i] \geq 3$ ;
  - constraint  $\text{not}(a[i] < 2)$ ;
  - constraint  $a[i] \geq 2 \rightarrow a[i] \leq 3$ ;

# Relational semantics

- A partial function creates answer false
  - at the nearest enclosing Boolean context

- Examples

- $1 \neq 1 \text{ div } 0$
- $\text{not}(1 == 1 \text{ div } 0)$
- $0 < 1 \vee 1 \text{ div } 0 \neq 1$
- $a[0] \geq 3$
- $\text{not}(a[0] < 2)$
- $a[0] \geq 2 \rightarrow a[0] \leq 3$

*false*

*not(false) = true*

*true  $\vee$  false = true*

*false*

*not(false) = true*

*false  $\rightarrow$  false = true*

# Efficiency in MiniZinc

- Of course as well as correctly modelling our problem we also want our MiniZinc model to be solved efficiently
- Information about efficiency is obtained using the MiniZinc flags
  - solver-statistics [number of choice points]
  - statistics [number of choice points, memory and time usage]
- Extensive experimentation is required to determine relative efficiency

# Improving Efficiency in MiniZinc

- Add **search annotations** to the solve item to control exploration of the search space.
- Use **global constraints** such as `alldifferent` since they have better propagation behaviour.
- Try **different models** for the problem.
- Add **redundant** constraints.

And for the expert user:

- Extend the constraint solver to provide a **problem specific global constraint**.
- Extend the constraint solver to provide a **problem specific search routine**.

# Modelling Effectively

- Modelling is (like) programming
  - You can write efficient and inefficient models
- Take care to avoid some simple traps
  - Bound variables as tightly as possible
    - Avoid var int if possible
  - Avoid introducing unnecessary variables
  - Make loops as tight as possible

# Bound your variables

```
var int: x;
```

```
var int: y;
```

```
constraint x <= y  $\wedge$  x > y;
```

```
solve satisfy;
```

- Takes an awful long time to say no answer

```
var -1000..1000: x;
```

```
var -1000..1000: y;
```

- Is almost instant

# Unconstrained variables

```
include "all_different.mzn";  
array[1..15] of var bool: b;  
array[1..4] of var 1..10: x;  
constraint alldifferent(x) /\  
    sum(i in 1..4)(x[i]) = 9;  
solve satisfy;
```

- Takes a long time to say no
- Remove the bool array its instant!
- Sometimes unconstrained vars arise from matrix models where not all vars are used

# Efficient loops

- Think about loops, just like in other programs

```
int: count = sum [1 | i, j, k in NODES where i < j  
    & j < k & adj[i,j] & adj[i,k] & adj[j,k]];
```

- Compare this to

```
int: count = sum( i, j in NODES where  
    i < j & adj[i,j])(  
    sum([1 | k in NODES where j < k  
        & adj[i,k] & adj[j,k]]));
```



# Global Constraints

- Where possible you should use global constraints
- MiniZinc provides a standard set of global constraints in the file `globals.mzn`
- To use these you simply include the file in the model  
`include "globals.mzn"`
- **Exercise:** Rewrite N-queens to use `all_different`.
- **Exercise:** Look at `globals.mzn`

# Different Problem Modellings

- Different views of the problem lead to **different models**
- Depending on solver capabilities one model may require less search to find answer
- Look for model with **fewer variables**
- Look for **more direct mapping** to primitive constraints.
- **Empirical comparison** may be needed

# Different Problem Modellings

Simple **assignment problem**:

- $n$  workers and
- $n$  products
- Assign one worker to each product to maximize profit

**Instance:**

$n=4$  & profit matrix =

	$p1$	$p2$	$p3$	$p4$
$w1$	7	1	3	4
$w2$	8	2	5	1
$w3$	4	3	7	2
$w4$	3	1	6	3

Exercise: Model this in MiniZinc

# MIP-style model

```
int: n;  
array[1..n,1..n] of int: profit;  
array[1..n,1..n] of var 0..1: assign;  
constraint  
  forall(w in 1..n) (  
    sum(t in 1..n) (assign[t,w]) = 1 );  
constraint  
  forall(t in 1..n) (  
    sum(w in 1..n) (assign[t,w]) = 1 );  
solve maximize  
  sum( w in 1..n, t in 1..n) (  
    assign[t,w]*profit[t,w]);
```

# Assign task to worker

```
include "globals.mzn";  
int: n;  
array[1..n,1..n] of int: profit;  
array[1..n] of var 1..n: task;  
  
constraint alldifferent(task);  
solve maximize  
  sum(w in 1..n) (  
    profit[w,task[w]]);
```

# Assign worker to task

```
include "globals.mzn";  
int: n;  
array[1..n,1..n] of int: profit;  
array[1..n] of var 1..n: worker;  
  
constraint alldifferent(worker);  
solve maximize  
  sum(t in 1..n) (  
    profit[worker[t],t]);
```

# Redundant Constraints

- Sometimes solving behaviour can be improved by adding **redundant** constraints to the model
- The magic series model will run faster with redundant constraints:

```
int: n;  
array[0..n-1] of var 0..n: s;
```

```
constraint  
forall(i in 0..n-1) (  
    s[i] = sum(i in 0..n-1)(bool2int(s[j]=i)));
```

```
constraint  
sum(i in 0..n-1) (s[i]) = n;
```

```
constraint  
sum(i in 0..n-1) (s[i]*i) = n;
```

```
solve satisfy;
```

# Redundant Constraints

- An extreme kind of redundancy is to combine different models for a problem using **channeling** constraints.

```
int: n;
array[1..n,1..n] of int: profit;
array[1..n] of var 1..n: task;
array[1..n] of var 1..n: worker;
constraint alldifferent(task);
constraint alldifferent(worker);
constraint
  forall( w in 1..n) (w = worker[task[w]]);
constraint
  forall( t in 1..n) (t = task[worker[t]]);
solve maximize
  sum(t in 1..n) (
    profit[worker[t],t]);
```



# Redundant Constraints

- There are globals for **channeling** constraints.
  - $\text{inverse}(x,y): x[i] = j \leftrightarrow y[j] = i$

- A better combined model

```
int: n;  
Include "inverse.mzn";  
array[1..n,1..n] of int: profit;  
array[1..n] of var 1..n: task;  
array[1..n] of var 1..n: worker;  
% constraint alldifferent(task); % redundant  
% constraint alldifferent(worker);  
constraint inverse(task,worker);  
solve maximize sum(t in 1..n) (profit[worker[t],t]);
```

# Extending the Constraint Solver

- MiniZinc can be executed using ECLiPSe, Mercury G12 solving platform, or Gecode.
- These allow new global constraints to be added to the solver
- They also allow new search strategies to be added
  - we'll talk about search strategies later

# Summary

- Advanced models in MiniZinc use predicates to define complex subproblem constraints
  - Global constraints (give better solving)
  - User defined constraints & tests (Give better readability)
- We need to be **careful** with negation and local variables
- Efficiency depends on the model formulation
- Developing an efficient decision model requires considerable experimentation

# Zinc

- However MiniZinc is not a very powerful modelling language.
- MiniZinc is a subset of [Zinc](#).
- Zinc extends MiniZinc providing
  - Tuples, enumerated constants, records, discriminated union
  - Var sets over arbitrary finite types
  - Arrays can have arbitrary index sets.
  - Overloaded functions and predicates.
  - Constrained types
  - User defined functions.
  - More powerful search parameterized by functions.
- Coming soon...

# Exercise 1: Predicates

- Write a predicate definition for
  - `near_or_far(var int:x, var int:y, int:d1, int:d2)`  
which holds if difference in the value of x and y is either at most d1 or at least d2.
  - Can you optimize its definition for simple cases?
- Write a predicate definition for
  - `sum_near_or_far(array[int] of var int:x, int: d1, int:d2)`  
which holds if the sum of the x array is at most d1 or at least d2

# Exercise 2: Comparing Models

- Try out the different versions of the assignment problem on the problems from examples.pdf (add an extra worker G to the unbalanced example with costs all 30)
  - Compare the number of choices required to solve using `mzn -statistics`
  - Try all five models, which is best?
  - Try different solvers?